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**PROGRAM TERROR**

An application of TRAMO to the detection  
of errors in time series

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## 1. INTRODUCTION

This note contains a brief description of program TERROR (Tramo for ERRORS). For a more complete description of the procedures, see the manual of program TRAMO ("Time series Regression with Arima noise, Missing observations, and Outliers" by V. Gómez and A. Maravall.)

Program TERROR is designed to handle large sets of time series with a monthly or lower frequency of observation.

For each series, the program automatically identifies an ARIMA model and detects and corrects for several types of outliers. (It also interpolates missing observations if there are any.) Next, the one-period-ahead forecast of the series is computed and compared with the new observation (this new observation is not used for estimation). In brief, when the forecast error is, in absolute value, larger than some a priori specified limit, the new observation is identified as a possible error.

The model obtained by TERROR for each series to compute the forecast is of the following type.

Given the vector of observations:

$$z = (z_{t_1}, \dots, z_{t_M}) \quad (1)$$

where  $0 < t_1 < \dots < t_M$ , the program fits the model

$$z_t = y'_t \omega + v_t, \quad (2)$$

where  $\omega = (\omega_1, \dots, \omega_n)'$  is a vector of regression coefficients,  $y'_t = (y_{1t}, \dots, y_{nt})$  denotes  $n$  regression variables, and  $v_t$  follows the general ARIMA process

$$\phi(B) \delta(B) v_t = \Theta(B) a_t, \quad (3)$$

where  $B$  is the backshift operator;  $\phi(B)$ ,  $\delta(B)$ , and  $\Theta(B)$  are finite polynomials in  $B$ , and  $a_t$  is assumed a n.i.i.d.  $(0, \sigma_a^2)$  white-noise innovation.

The polynomial  $\delta(B)$  contains the unit roots associated with differencing (regular and seasonal),  $\phi(B)$  is the polynomial with the stationary autoregressive roots (and the complex unit roots, if present), and  $\Theta(B)$  denotes the (invertible) moving average polynomial. In TERROR, they assume the following multiplicative form:

$$\delta(\mathbf{B}) = (1 - \mathbf{B})^d (1 - \mathbf{B}^s)^D$$

$$\phi(\mathbf{B}) = (1 + \phi_1 \mathbf{B} + \dots + \phi_p \mathbf{B}^p) (1 + \phi_1 \mathbf{B}^s + \dots + \phi_p \mathbf{B}^{s \times p})$$

$$\Theta(\mathbf{B}) = (1 + \Theta_1 \mathbf{B} + \dots + \Theta_q \mathbf{B}^q) (1 + \Theta_1 \mathbf{B}^s + \dots + \Theta_q \mathbf{B}^{s \times q}),$$

where  $s$  denotes the number of observations per year. The model may contain a constant  $\mu$ , equal to the mean of the differenced series  $\delta(\mathbf{B}) z_t$ . In practice, this parameter is estimated as one of the regression parameters in (2).

The regression variables are outliers automatically identified by the program. Thus, if there are  $J$  outliers, occurring at periods  $T_1, \dots, T_j$ , the regression term can be expressed as

$$y'_t \omega = \sum_{i=1}^J \omega_i \lambda_i(\mathbf{B}) I_t^{(Ti)},$$

where  $I_t^{(Ti)}$  is a dummy variable equal to 1 when  $t=T_i$ , and zero otherwise. The polynomial  $\lambda_i(\mathbf{B})$  specifies the type of outlier detected. Three types are considered:

Additive outlier:  $\lambda(\mathbf{B}) = 1$

Level shift :  $\lambda(\mathbf{B}) = 1 / \nabla$

Transitory change:  $\lambda(\mathbf{B}) = 1 / (1 - \delta \mathbf{B})$ ,

where  $0 < \delta < 1$ , and by default  $\delta = .7$ .

The additive outlier represents a one-period spike, the level shift represents a step function, and the transitory change is as an additive outlier that gradually disappears over several periods.

## 2. INPUT FILE AND INPUT PARAMETERS

### 2.1 Parameters fixed in TRAMO

In the DOS version, the **input file** is of the type ITER = 2, i.e., the same input namelist applies to all series. The program fixes several parameters in TRAMO, namely the following ones.

<u>Parameter</u>	<u>Meaning</u>
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#### **Automatic ARIMA Model Identification**

IDIF = 3	Used for automatic model identification. The program searches first for regular differences up to order 2 and for seasonal differences up to order 1. Then, it continues with the identification of an ARMA model for the differenced series.
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INIC = 3	The program searches for regular polynomials up to order 3, and for seasonal polynomials up to order 1.
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#### **Automatic detection and correction of three types of outliers** (level shifts, transitory changes, and Additive Outliers)

AIO = 2	Additive Outliers, Transitory Changes, and Level Shifts are considered.
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IATIP = 1	Automatic detection and correction of outliers is performed. After correcting for the outliers found in the first round, the program performs a new automatic model identification, and a new search for outliers if the model has been changed. In this second round, the critical value VA is reduced by the fraction .14. If the second round does not provide a satisfactory model, a third round is carried out. (The model obtained with automatic identification is always compared with the default model.)
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#### **Pre-test for log level specification**

LAM = -1	The program tests for the log-level specification. The test is based, first, on the slope (b) of a range-mean regression, "trimmed" to avoid outlier distortion. This slope b is compared to a constant ( $\beta$ ), close to zero, that depends on the number of observations and on the value of RSA. When the results of the regression are unclear, the value of LAM is chosen according to the BIC of the default model, using both specifications.
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<u>Parameter</u>	<u>Meaning</u>
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Additional parameters that are fixed:

NBACK = -1 The last observation is omitted from the end of the series. The model is estimated for the shorter series and the one-period-ahead forecast error is computed for the last period (without reestimation of the model) as well as the associated t-value.

INTERP = 1 Interpolates missing values (if any)

ITER = 2 The same input namelist applies to all series in the file.

## 2.2 Other input parameters from TRAMO

The TRAMO parameters that are not part of the fixed input configuration can be entered if one wishes to modify their default value. The most relevant ones are the following:

<u>Parameter</u>	<u>Meaning</u>
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MQ = Number of observations per year (12 for monthly, 6 for bimonthly, 4 for quarterly, 1 for annual, and so on).  
Default = 12

VA = Used to set the critical value for outlier detection.  
The default values are as follows:

$NZ \leq 50,$	$VA = 3$
$50 < NZ \leq 250,$	$VA = 3.5$
$250 < NZ \leq 500,$	$VA = 3.8$
$500 < NZ$	$VA = 4$

INT2 = Two parameters, INT1 and INT2, can be used to define the interval (INT1, INT2) over which outliers have to be searched. By default

$$INT1 = 1; \quad INT2 = NZ.$$

A facility has been introduced to avoid outlier correction in the last observations of the series, which may cause instability in the series forecasts. In particular:

<u>Parameter</u>	<u>Meaning</u>
	<p>When <math>INT2 = -k &lt; 0</math>, outliers are automatically detected and corrected in the interval <math>(INT1, NZ - k)</math>. Then, the detection procedure is applied to the last <math>k</math> observations, and if some outlier is detected a warning is printed, but no correction is made. Example: if <math>NZ = 47</math> and <math>INT2 = -2</math>, outliers are detected and corrected for the interval <math>(1, 45)</math>. For the last 2 observations they are only detected. Since <math>NBACK = -1</math>, observation 47 is deleted from the sample estimation period, and hence in this case <math>INT2 = -2</math> implies that outliers, if detected, will not be corrected for the last observation of the sample estimation period (observation 46).</p> <p>Detection and correction of outliers is made with a procedure based on those of Tsay (1986) and Chen and Liu (1993). This procedure has some notable features (namely, exact residuals are used; estimation, based on two simple regressions, is fast; the parameter estimates are modified at each iteration; and it uses a robust method to incorporate or reject outliers which is similar to the stepwise regression procedure to select the "best" regression equation).</p> <p>In automatic outlier identification and correction and automatic model identification, the sequence of actions is as follows. After obtaining the degrees of differencing automatically (<math>IDIF = 3</math>), the program obtains first a model using the BIC criterion and then performs the automatic identification and correction of outliers using the previously identified model. There are two rounds: first, the program uses this model to correct the series for the outlier effects. Then, it returns to model identification and further outlier identification and correction, using the model obtained in the second round and a critical level equal to .86 times that of the first round.</p>
INCON = 0	Exact maximum likelihood estimation
= 1	Unconditional least squares.
	Default = 0
IMVX = 0	The fast method of Hannan-Rissanen is used for parameter estimation in the automatic detection and correction of outliers
= 1	Maximum likelihood estimation is used for parameter estimation in the automatic detection and correction of outliers
	Default = 0

### 2.3 New input parameters

TERROR is mostly controlled by the parameter SENS, which determines how sensitive should be the detection of errors, according to the following values.

SENS = 0    Low sensitivity;  
      = 1    Medium sensitivity;  
      = 2    High sensitivity.

The default value is 1.

The parameter SENS sets two parameters,  $k_1$  and  $k_2$ .

Let  $t$  = forecast error/standard derivation of residuals. Then:

If, for a particular series,

$|t| > k_2$ ,    the new observation in the series is classified as "likely" to contain an error.

If

$k_1 < |t| \leq k_2$ ,    the new observation is classified as containing a "possible" error.

If

$|t| \leq k_1$ ,    the new observation is accepted as without error.

The values of  $k_1$  and  $k_2$  for the different levels of sensitivity are as follows:

SENS = 0	$k_1 = 4$	$k_2 = 5$
SENS = 1	$k_1 = 3.9$	$k_2 = 4.42$
SENS = 2	$k_1 = 3.3$	$k_2 = 3.9$

These values can be changed. To do that, set

SENS  $\geq 3$ ,

then you can enter the new values of  $k_1$  and/or  $k_2$ .

### 3. INPUT FILE

The input file should be named serie, and should have the structure of an ITER = 2 file (see TRAMO User Instructions). In particular, the line with the input namelist should only appear once, after the first serie in the file. As described above, all parameters are fixed or set by default and the INPUT NAMELIST should only contain the parameters (not fixed) that depart from the default value.

The input file consists of a sequence of series; for each series, the maximum numbers of observations is 600, and the minimum 15. Each serie should be entered as follows:

First line: J TITLE (no more than 72 characters)

Second line: NZ NYEAR NPER (free format)

Third line et seq.: Z(I) : I = 1,..., NZ (free format), where J refers to the order of the series in the file (J = 10 denotes the tenth series), NZ is the number of observations, NYEAR is the starting year, and NPER is the starting period of the year (if series is monthly, 1 for January, 2 for February, and so on), Z(.) is the array (or matrix) of observations. For each missing observation, the code -99999. must be entered.

The first series is followed by the INPUT namelist, entered as follows:

\$INPUT parameter = parameter value ... \$,

where only non-fixed, non-default parameter values need to be entered. The format "\$...\$" can be replaced by others such as "&.../". The INPUT namelist is entered after the first series.

An example of an input file is presented. The fixed configuration of ERROR will apply. The only parameters that depart from their default value are

- a) MQ = 4, which specifies that the series are quarterly ones (default is monthly).
- b) INT2 = -2, which specifies that, for the last two observations of the series, outliers are only detected but not corrected.

Notice that the third series contains holes corresponding to missing values.



## EXAMPLE OF INPUT FILE

1            0012-ARGELIA,A14-ACT.TOTAL-PTS. + M.EXTRANJERA,TO  
48 1986 1

77485	72684	70303	66187
64519	61316	59160	56160
55040	52270	52005	48887
47371	46850	47198	47239
47345	46775	48923	50012
58136	65971	67761	67319
95307	89150	95727	122034
143982	155044	168047	174882
184586	187004	185379	180137
164085	145485	137217	126161
125174	120003	107599	103621
106805	105384	100703	97806

\$INPUT MQ=4 INT2=-2 \$

2            0020-ANDORRA,A14-ACT.TOTAL-PTS. + M.EXTRANJERA,TO  
48 1986 1

12389	8227	8627	16277
13296	5263	9281	9769
10380	17787	11064	7650
18701	8517	9156	9114
20940	12368	11669	12704
13029	13679	11033	9951
10794	9565	10187	13187
13498	19958	20268	30502
40780	40261	31394	29658
31537	38386	39725	33322
38434	33550	36786	20566
22848	23870	36492	33538

3            0024-ANGOLA,A14-ACT.TOTAL-PTS. + M.EXTRANJERA,TO  
48 1986 1

11818	10910	9857	10542
10640	-99999	-99999	14060
12938	-99999	13340	11574
12038	13572	-99999	-99999
12389	11901	13292	15877
15177	18517	17014	19784
20751	25736	39555	48067
56396	63402	63886	62345
56001	47451	39780	35479
30810	28343	26995	27825
26382	25333	24117	22783
26999	28101	28883	37710

4            0032-ARGENTINA,A14-ACT.TOTAL-PTS. + M.EXTRANJERA,TO  
48 1986 1

95915	95132	90424	87995
83089	78520	73128	70696
69726	74866	79512	77214
77841	74953	71186	66207
66372	54533	56834	50212
64001	63282	59404	60801
63065	58750	60839	73021
78635	77720	77284	99295
106840	110325	101370	80381
84523	85920	84708	96051
97306	104271	114889	179567
207081	244191	249611	366232

#### 4. OUTPUT FILE

TERROR produces the output file list.out in the directory TERROR\OUTPUT. The file consists of two sets of pairs of numbers, each pair given in brackets. The first set contains the series for which  $|t| > k_2$ , that is the series "likely" to contain an error. The second set contains the series for which  $k_1 < |t| \leq k_2$ , that is the series for which an error is "possible".

Each bracket contains two numbers. The first one gives the position of the series in the list of series contained in the input file. The second number is the  $t$  value of the forecast error. Thus  $\{ 4, 6.32 \}$  indicates that the 4th series is likely to have an error, since  $t=6.32$ .

An example of a list.out file is provided. It specifies that the program has been applied to a file with 436 series, with  $k_1$  and  $k_2$  set at their default values (the ones implied by  $\text{SENS} = 1$ ). Of the 436 series, 28 are candidates for a likely error (the first candidate, is series 192, with the largest value of  $t$ , equal to 16.32). The set of possible errors provides 8 additional series.

All series were processed without error.

## EXAMPLE OF THE OUTPUT FILE

SERIES

436 K1= 3.900 K2= 4.420

Likely =

```
{ 4, 6.32}, { 24, -5.36}, { 27, 10.75}, { 32, 7.56},
{ 45, 5.74}, { 52, 6.32}, { 88, 11.28}, { 92, -8.13},
{ 95, 6.87}, { 106, 5.48}, { 114, -5.55}, { 135, 12.81},
{ 140, 7.57}, { 143, 4.72}, { 163, 5.94}, { 172, 12.70},
{ 192, 16.32}, { 198, 14.14}, { 248, 5.41}, { 267, 6.92},
{ 281, 8.70}, { 283, 5.74}, { 308, 12.50}, { 345, 5.95},
{ 352, 13.96}, { 358, 4.64}, { 370, 4.51}, { 391, 7.69},
```

AENP = 0.05

Possible =

```
{ 57, -4.33}, { 112, 4.04}, { 132, -3.94}, { 134, 3.99},
{ 160, -4.04}, { 187, 4.20}, { 215, -4.26}, { 266, -4.00},
```

AENL = 0.00

NDP Exception =

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